

Package: RGeode (via r-universe)

September 6, 2024

Version 0.1.0

Date 2017-08-24

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Title Geometric Density Estimation

Description Provides the hybrid Bayesian method Geometric Density Estimation. On the one hand, it scales the dimension of our data, on the other it performs inference. The method is fully described in the paper "Scalable Geometric Density Estimation" by Y. Wang, A. Canale, D. Dunson (2016) <<http://proceedings.mlr.press/v51/wang16e.pdf>>.

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Depends R (>= 3.0.0), Rcpp (>= 0.12.11), MASS (>= 7.3-47), stats (>= 3.4.1)

LinkingTo Rcpp

RoxygenNote 6.0.1

Repository <https://lorenzorimella.r-universe.dev>

RemoteUrl <https://github.com/lorenzorimella/rgeode>

RemoteRef HEAD

RemoteSha 7158c767cd6692b66fb88f9802896a0d4b0c776e

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p	<i>Threshold probability (p(t))</i>
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Description

The decreasing function for the adaptive pruning.

Usage

`p(t, c0, c1)`

Arguments

t	int	The current iteration at which the probability of an adaptation is calculated.
c0	double	Additive constant at the exponent-
c1	double	Multiplicative constant at the exponent.

Value

p returns the threshold of interest:

p(t)	double	It is $p(t) = \exp(c0) + c1 * t$.
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References

- [1] A. Canale, D. Dunson, Y. Wang. "Scalable Geometric Density Estimation" (2016). (available at <https://arxiv.org/abs/1410.7692>). The implementation of `rgammatr` is inspired to the Matlab implementation of `rexprunc` by Ye Wang.

Examples

```
t = 10
c0 = -1
c1 = 10

p(t, c0, c1)
```

randSVD	<i>Randomized Singular Value Decomposition.</i>
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Description

Compute the near-optimal low-rank singular value decomposition (SVD) of a rectangular matrix. The algorithm follows a randomized approach.

Usage

```
randSVD(A, k = NULL, l = NULL, its = 2, sdist = "unif")
```

Arguments

A	array_like a real/complex input matrix (or data frame), with dimensions (m, n) . It is the real/complex matrix being approximated.
k	int, optional determines the target rank of the low-rank decomposition and should satisfy $k \ll \min(m, n)$. Set by default to 6.
l	int, optional block size of the block Lanczos iterations; l must be a positive integer greater than k , and defaults $l = k + 2$.
its	int, optional number of full iterations of a block Lanczos method to conduct; its must be a nonnegative integer, and defaults to 2.
sdist	str c('normal', 'unif'), optional Specifies the sampling distribution. 'unif': (default) Uniform '[-1,1]'. 'normal': Normal '~N(0,1)'.

Details

Randomized SVD (randSVD) is a fast algorithm to compute the approximate low-rank SVD of a rectangular (m, n) matrix A using a probabilistic algorithm. Given the decided rank $k \ll n$, rSVD factors the input matrix A as $A = U * \text{diag}(S) * V'$, which is the typical SVD form. Precisely, the columns of U are orthonormal, as are the columns of V , the entries of S are all nonnegative, and the only nonzero entries of S appear in non-increasing order on its diagonal. The dimensions are: U is (m, k) , V is (n, k) , and S is (k, k) , when A is (m, n) .

Increasing its or l improves the accuracy of the approximation USV' to A .

The parameter its specifies the number of normalized power iterations (subspace iterations) to reduce the approximation error. This is recommended if the the singular values decay slowly. In practice 1 or 2 iterations achieve good results, however, computing power iterations increases the computational time. The number of power iterations is set to $its = 2$ by default.

Value

randSVD returns a list containing the following three components:

d	array_like (k, k) matrix in the rank- k approximation USV' to A , where A is (m, n); the entries of S are all nonnegative, and its only nonzero entries appear in nonincreasing order on the diagonal.
u	matrix (m, k) matrix in the rank- k approximation $A = U * diag(S) * V'$ to A ; the columns of U are orthonormal and are called Left singular vect. We want to remark that this is the transpose matrix, hence the vectors are on the rows of our matrix.
v	matrix (n, k) matrix in the rank- k approximation $A = U * diag(S) * V'$ to A ; the columns of V are orthonormal and are called Right singular vect.

Note

The singular vectors are not unique and only defined up to sign (a constant of modulus one in the complex case). If a left singular vector has its sign changed, changing the sign of the corresponding right vector gives an equivalent decomposition.

Author(s)

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References

- [1] N. Halko, P. Martinsson, and J. Tropp.
"Finding structure with randomness: probabilistic algorithms for constructing approximate matrix decompositions" (2009).
(available at arXiv <http://arxiv.org/abs/0909.4061>).
- [2] S. Voronin and P. Martinsson.
"RSVDPACK: Subroutines for computing partial singular value decompositions via randomized sampling on single core, multi core, and GPU architectures" (2015).
(available at arXiv <http://arxiv.org/abs/1502.05366>).
- [3] N. Benjamin Erichson.
"Randomized Singular Value Decomposition (rsvd): R package" (2016).
(available in the CRAN).
- [4] Nathan Halko, Per-Gunnar Martinsson, and Joel Tropp.
"Finding structure with randomness: Stochastic algorithms for constructing approximate matrix decompositions" (2009).
(available at <http://arxiv.org>).
- [5] V. Rokhlin, A. Szlam, M. Tygert.
"A randomized algorithm for principal component analysis" (2009).
(available at <https://arxiv.org/abs/0809.2274>).
The implementation of rand SVD is inspired by the MatLab implementation of RandPCA by M. Tygert.

Examples

```
#Simulate a general matrix with 1000 rows and 1000 columns
vy= rnorm(1000*1000,0,1)
y= matrix(vy,1000,1000,byrow=TRUE)

#Compute the randSVD for the first hundred components of the matrix y and measure the time
start.time <- Sys.time()
prova1= randSVD(y,k=100)
Sys.time()- start.time

#Compare with a classical SVD
start.time <- Sys.time()
prova2= svd(y)
Sys.time()- start.time
```

rexpnr

Random generator for a Truncated Exponential distribution.

Description

Simulate random number from a truncated Exponential distribution.

Usage

```
rexpnr(n = 1, lambda = 1, range = NULL)
```

Arguments

n	int, optional number of simulations.
lambda	double, optional parameter of the distribution.
range	array_like, optional domain of the distribution, where we truncate our Exponential. <i>range(0)</i> is the min of the range and <i>range(1)</i> is the max of the range.

Details

It provide a way to simulate from a truncated Exponential distribution with given parameter λ and the range *range*. This will be used during the posterior sampling in th Gibbs sampler.

Value

rexpnr returns the simulated value of the distribution:

u	double it is the simulated value of the truncated Exponential distribution. It will be a value in $(range(0), range(1))$.
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References

- [1] Y. Wang, A. Canale, D. Dunson. "Scalable Geometric Density Estimation" (2016). The implementation of rgammatr is inspired to the Matlab implementation of rexp trunc by Ye Wang.

Examples

```
#Simulate a truncated Exponential with parameters 0.5 in the range
#5,Inf.
#Set the range:
range<- c(1,Inf)

#Simulate the truncated Gamma
set.seed(123)
vars1<-rexp(1000,0.5,range)

#Look at the histogram
hist(vars1,freq=FALSE,ylim=c(0,2),xlim = c(0,5))
lines(density(vars1))

#Compare with a non truncated Exponential
set.seed(123)
vars2<-rexp(1000,0.5)

#Compare the two results
lines(density(vars2),col='red')

#Observation: simulate without range is equivalent to simulate from
#rexp(1000,0.5)
```

rgammatr

Random generator for a Truncated Gamma distribution.

Description

Simulate random number from a truncated Gamma distribution.

Usage

```
rgammatr(n = 1, A = 0, B = 1, range = NULL)
```

Arguments

n	int, optional number of simulations.
A	double, optional shape parameter of the distribution.
B	double, optional rate parameter of the distribution.
range	array_like, optional domain of the distribution, where we truncate our Gamma. $range(0)$ is the min of the range and $range(1)$ is the max of the range.

Details

It provide a way to simulate from a truncated Gamma distribution with given parameters A , B and range $range$. This will be used during the posterior sampling in th Gibbs sampler.

Value

rgammatr returns the simulated value of the distribution:

u	double it is the simulated value of the truncated Gamma distribution. It will be a value in $(range(0), range(1))$.
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References

- [1] Y. Wang, A. Canale, D. Dunson. "Scalable Geometric Density Estimation" (2016).
The implementation of rgammatr is inspired to the Matlab implementation of gamrndtruncated by Ye Wang.

Examples

```
#Simulate a truncated Gamma with parameters 1,2 in the range
#1,5.
#Set the range:
range<- c(1,5)

#Simulate the truncated Gamma
set.seed(123)
vars1<-rgammatr(1000,1,2,range)

#Look at the histogram
hist(vars1,freq=FALSE,ylim=c(0,2),xlim = c(0,5))
lines(density(vars1))
```

```
#Compare with a non truncated Gamma
set.seed(123)
vars2<-rgamma(1000,1,2)

#Compare the two results
lines(density(vars2),col='red')

#Observation: simulate without range is equivalent to simulate from
#rgamma(1000,1,2)
```

rgeode

GEOMETRIC DENSITY ESTIMATION.

Description

It selects the principal directions of the data and performs inference. Moreover GEODE is also able to handle missing data.

Usage

```
rgeode(Y, d = 6, burn = 1000, its = 2000, tol = 0.01, atau = 1/20,
       asigma = 1/2, bsigma = 1/2, starttime = NULL, stoptime = NULL,
       fast = TRUE, c0 = -1, c1 = -0.005)
```

Arguments

Y	array_like a real input matrix (or data frame), with dimensions (n, D) . It is the real matrix of data.
d	int, optional it is the conservative upper bound for the dimension D . We are confident that the real dimension is smaller then it.
burn	int, optional number of burn-in to perform in our Gibbs sampler. It represents also the stopping time that stop the choice of the principal axes.
its	int, optional number of iterations that must be performed after the burn-in.
tol	double, optional threshold for adaptively removing redundant dimensions. It is used compared with the ratio: $\frac{\alpha_j^2(t)}{\max \alpha_i^2(t)}$.
atau	double, optional The parameter a_τ of the truncated Exponential (the prior for τ_j).
asigma	double, optional The shape parameter a_σ of the truncated Gamma (the prior for σ^2).

bsigma	double, optional The rate parameter b_σ of the truncated Gamma (the prior for σ^2).
starttime	int, optional starting time for adaptive pruning. It must be less then the number of burn-in.
stoptime	int, optional stop time for adaptive pruning. It must be less then the number of burn-in.
fast	bool, optional If <i>TRUE</i> it is run using fast d-rank SVD. Otherwise it uses the classical SVD.
c0	double, optional Additive constant for the exponent of the pruning step.
c1	double, optional Multiplicative constant for the exponent of the pruning step.

Details

GEOmetric Density Estimation (rgeode) is a fast algorithm performing inference on normally distributed data. It is essentially divided in two principal steps:

- Selection of the principal axes of the data.
- Adaptive Gibbs sampler with the creation of a set of samples from the full conditional posteriors of the parameters of interest, which enable us to perform inference.

It takes in inputs several quantities. A rectangular (N, D) matrix Y , on which we will run a Fast rank d SVD. The conservative upper bound of the true dimension of our data d . A set of tuning parameters. We remark that the choice of the conservative upper bound d must be such that $d > p$, with p real dimension, and $d \ll D$.

Value

rgeode returns a list containing the following components:

InD	array_like The chose principal axes.
u	matrix Containing the sample from the full conditional posterior of u_j s. We store each iteration on the columns.
tau	matrix Containing the sample from the full conditional posterior of tau_j s.
sigmaS	array_like Containing the sample from the full conditional posterior of $sigma$.
W	matrix Containing the principal singular vectors.
Miss	list Containing all the informations about missing data. If there are not missing data this output is not provide. <ul style="list-style-type: none"> • id_m array It contains the set of rows with missing data.

- pos_m list
It contains the set of missing data positions for each row with missing values.
- yms list
The list contained the pseudo-observation substituting our missing data. Each element of the list represents the simulated data for that time.

Note

The part related to the missing data is filled only in the case in which we have missing data.

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References

- [1] Y. Wang, A. Canale, D. Dunson. "Scalable Geometric Density Estimation" (2016).

Examples

```
library(MASS)
library(RGeode)

#####
# WITHOUT MISSING DATA
#####
# Define the dataset
D= 200
n= 500
d= 10
d_true= 3

set.seed(321)

mu_true= runif(d_true, -3, 10)

Sigma_true= matrix(0,d_true,d_true)
diag(Sigma_true)= c(runif(d_true, 10, 100))

W_true = svd(matrix(rnorm(D*d_true, 0, 1), d_true, D))$v

sigma_true = abs(runif(1,0,1))

mu= W_true%%mu_true
C= W_true %% Sigma_true %% t(W_true)+ sigma_true* diag(D)

y= mvrnorm(n, mu, C)

#####
# GEODE: Without missing data
```

```
#####

start.time <- Sys.time()
GEODE= rgeode(Y= y, d)
Sys.time()- start.time

# SIGMAS
#plot(seq(110,3000,by=1),GEODE$sigmaS[110:3000],ty='l',col=2,
#      xlab= 'Iteration', ylab= 'sigma^2', main= 'Simulation of sigma^2')
#abline(v=800,lwd= 2, col= 'blue')
#legend('bottomright',c('Posterior of sigma^2', 'Stopping time'),
#       lwd=c(1,2),col=c(2,4),cex=0.55, border='black', box.lwd=3)

#####
# WITH MISSING DATA
#####

#####
#Insert NaN
n_m = 5 #number of data vectors containing missing features
d_m = 1 #number of missing features

data_miss= sample(seq(1,n),n_m)

features= sample(seq(1,D), d_m)
for(i in 2:n_m)
{
  features= rbind(features, sample(seq(1,D), d_m))
}

for(i in 1:length(data_miss))
{

  if(i==length(data_miss))
  {
    y[data_miss[i],features[i,][-1]]= NaN
  }
  else
  {
    y[data_miss[i],features[i,]]= NaN
  }
}

#####
# GEODE: With missing data
#####
set.seed(321)
start.time <- Sys.time()
GEODE= rgeode(Y= y, d)
Sys.time()- start.time
```

```
# SIGMAS
#plot(seq(110,3000,by=1),GEODE$sigmaS[110:3000],ty='l',col=2,
#      xlab= 'Iteration', ylab= 'sigma^2', main= 'Simulation of sigma^2')
#abline(v=800,lwd= 2, col= 'blue')
#legend('bottomright',c('Posterior of sigma^2', 'Stopping time'),
#       lwd=c(1,2),col=c(2,4),cex=0.55, border='black', box.lwd=3)
```

```
#####
#####
```

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